

International Journal of
ARTIFICIAL INTELLIGENCE AND COMPUTATIONAL RESEARCH

VOLUME 7 • NUMBER 2 • DECEMBER 2015

CONTENTS



Kinematic Modeling of an Autonomous Wheeled Robot	63-73
<i>Dayal R. Parhi and Prases K. Mohanty</i>	
Review of Genetic-Fuzzy Methods used for Handling the Uncertainties in Fault Detection	75-81
<i>Dayal R. Parhi and Sasmita Sahu</i>	
Vibrational Analysis of Structures: A Review	83-94
<i>Dayal. R. Parhi and Shakti. P. Jena</i>	
Determination of Modified Natural Frequencies of Fractured Fixed-Fixed Beam by	95-101
Numerical & Experimental Method	
<i>Dayal R. Parhi and Deepak K. Agarwalla</i>	
A Review of Mobile Robot Localization and Navigation	103-109
<i>Dayal Ramakrushna Parhi and Anish Pandey</i>	
Parametric stability of a Multilayered Rotating Beam by Saito and Otomi conditions	111-119
<i>P. R. Dash and K. Ray</i>	
Multi-robot Cooperation based on ROI sharing for Distributed Cognition	121-133
<i>Rokunuzzaman, Abdul Kader, Mahmudul Hasan and Amit Roy</i>	
Multi-fault Source Localization in Motorcycles based on Wavelet Packets of the Sound Signals	135-150
<i>Basavaraj S. Anami and Veerappa B. Pagi</i>	