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Reg No.: Name:

### APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

FIFTH SEMESTER B.TECH DEGREE EXAMINATION, DECEMBER 2018

### **Course Code: EE303**

### **Course Name: LINEAR CONTROL SYSTEMS**

Max. Marks: 100 Duration: 3 Hours

### PART A

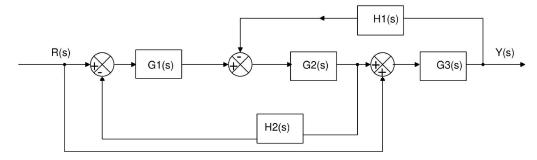
# Answer all questions, each carries 5 marks. Marks

- Derive the closed loop transfer function for a non-unity feedback system. (5)
- Write short notes on Force- voltage and Force current analogy? (5)
- Check the stability of the system given by the characteristic equation (5)  $P(s) = s^{5} + 2s^{4} + 4s^{3} + 8s^{2} + 16s + 32$
- What is magnitude and angle criterion? Determine whether the points (-4+j2) is on the root locus of a unity feedback system with forward transfer function K(s+2)
  - $G(s) = \frac{K(s+2)}{s^2 + 4s + 13}$ ?<br/>Define any three frequency response specifications used for the design of
- Define any three frequency response specifications used for the design of (5) control system?
- 6 Explain how the stability of a system is analysed using Bode plot? (5)
- 7 State and explain Nyquist stability criterion? (5)
- 8 Sketch the polar plot of type 1 second order system? (5)

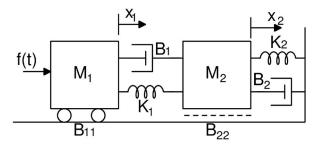
#### PART B

## Answer any two full questions, each carries 10 marks.

9 a) Obtain the transfer function using block diagram reduction techniques. (5)

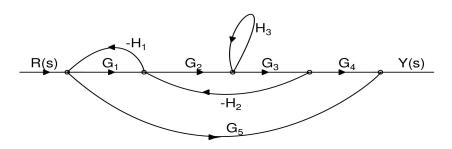


b) Derive the transfer function for the mechanical system shown in figure. (5)



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- 10 a) Derive an expression for the step response of a critically damped second order (4) system?
  - b) Determine the value of gain K and the natural frequency of oscillation  $\omega_n$  for the unity feedback system with forward transfer function  $G_p(s) = \frac{K}{s(s+10)}$ , which results in a critically damped response when subjected to a unit step input.
- 11 a) A unity feedback system is characterised by an open loop transfer function  $G_p(s) = \frac{20}{s^2 + 5s + 5}$ . Determine the transient response when subjected to a unit step input and sketch the response. Evaluate the maximum overshoot and the corresponding peak time of the system.
  - b) For the signal flow graph shown below, determine the transfer function. (5)



PART C
Answer any two full questions, each carries 10 marks.

- Consider a unity feedback system with an open loop transfer function  $\frac{K}{s(s+20)}$ .

  Determine the value K which would result in a steady state error of 0.05 for a unit ramp input.
  - b) Using Routh-Hurwitz criterion determine the value of K for which the closed (5) loop system transfer function  $\frac{K}{s^3 + 20s^2 + 80s + K}$  is stable, marginally stable and unstable.
- Sketch the root locus of a negative feedback system whose open loop transfer (10) function is given by  $\frac{K(s+4)}{s(s+1)(s+2)}$ . Determine the range of K for which the closed loop system is stable.
- 14 a) Determine the dynamic error coefficients for a unity feedback system whose open loop transfer function is  $\frac{20}{s(s+10)}$ , when subjected to an input of  $r(t) = 2 + t + 3t^2$ . Also compute the steady state error of the system.
  - a) Discuss about the effect of addition of poles and zeros to the open-loop transfer (4)

function G(s) H(s) on the root locus.

## **PART D**

## Answer any twofull questions, each carries 10 marks.

- 15 a) The open-loop transfer function of a unity feedback system is (10)  $\frac{K}{s(0.5s+1)(0.04s+1)}$ . Use asymptotic approach to plot the bode diagram and determine the value of K for a gain margin of 10.5 dB
- Draw the polar plot of open loop transfer function  $\frac{6}{(s+1)(s+2)}$  and determine the phase margin and gain margin. (10)
- 17 a) What is transportation lag in control system? (4)
  - Draw the bode plot for the transfer function given by  $\frac{5(s+2)}{s(s+10)}$ . Comment on the stability of the system

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